

Differential Geometry IV

Problem Set 1

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- (1) Let $n \in \mathbf{N}$. The ansatz $\not{D} = \sum_{i=1}^n \gamma_i \partial_{x_i}$ for the Dirac operator leads to system of algebraic equations

$$\gamma_i^2 = -1 \quad \text{and} \quad \gamma_i \gamma_j + \gamma_j \gamma_i = 0.$$

This admits no solutions in \mathbf{R} but it can be solved in complex matrices.

Find a solution for $n = 1$ and $n = 2$.

- (2) Let V be a vector space with $\dim V < \infty$. Let $b \in \text{Hom}(S^2V, \mathbf{R})$ by a symmetric bilinear form. Suppose that b is non-degenerate (that is: the induced map $V \rightarrow V^*, v \mapsto b(v, \cdot)$ is an isomorphism). Suppose that $W \subset V$ is isotropic (that is: the restriction of $b|_W \in \text{Hom}(S^2W, \mathbf{R})$ vanishes) and $\dim W = \frac{1}{2} \dim V$.

Prove that the signature $\sigma(b)$ of b vanishes. (*Hint:* Use a basis of W and b to construct a basis of V in which b becomes particularly simple but not diagonal, then diagonalise.)

- (3) Let X be a closed oriented manifold of dimension $4k$. Prove that there is an intersection form $b_X \in \text{Hom}(S^2H_{\text{dR}}^{2k}(X), \mathbf{R})$ satisfying $b_X([\alpha], [\beta]) = \int_X \alpha \wedge \beta$.

In particular, it makes sense to define $\sigma(X) := \sigma(b_X)$.

- (4) Prove that $\sigma(X \times Y) = \sigma(X)\sigma(Y)$.
- (5) Let Y be a compact oriented manifold with boundary $\partial Y = X$. Suppose that $\dim X = 4k$. Set $W := \text{im}(H_{\text{dR}}^{2k}(Y) \rightarrow H_{\text{dR}}^{2k}(X))$.

Prove that W is isotropic.

Prove that $\dim W = \frac{1}{2}b^{2k}(X)$. (*Hint:* Try to assemble the long exact sequence of relative homology, Poincaré duality, and Poincaré–Lefschetz duality into a commutative diagram.)

Prove that $\sigma(X) = 0$.

- (6) Let X be a smooth manifold with $\dim X = 2n$. Define $\varepsilon \in \text{End}(\Lambda T^*X \otimes \mathbf{C})$ by

$$\varepsilon \alpha := i^{k(k-1)+n} * \alpha \quad \text{with} \quad k := \deg \alpha.$$

Prove that:

- (a) $\varepsilon^2 = 1$
 - (b) $d + d^*$ and ε anti-commute.
- (7) Recall the Chern–Weil homomorphism (for example, from Differential Geometry III).
Prove that the first L polynomial is $L_1 = \frac{1}{3}p_1$.